



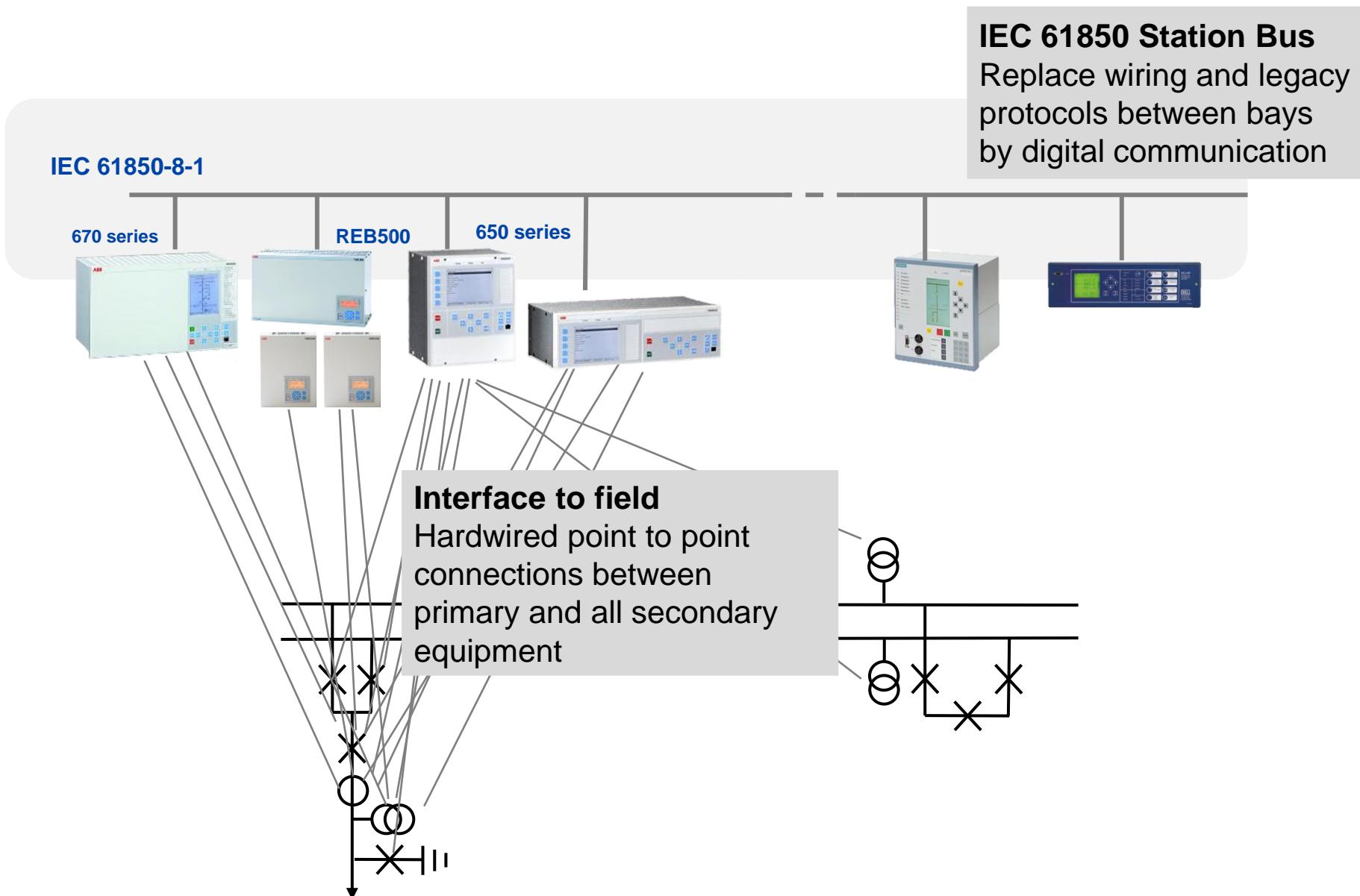
陳建良, 艾波比股份有限公司

# Merging Unit在智慧變電所之應用

# Substations

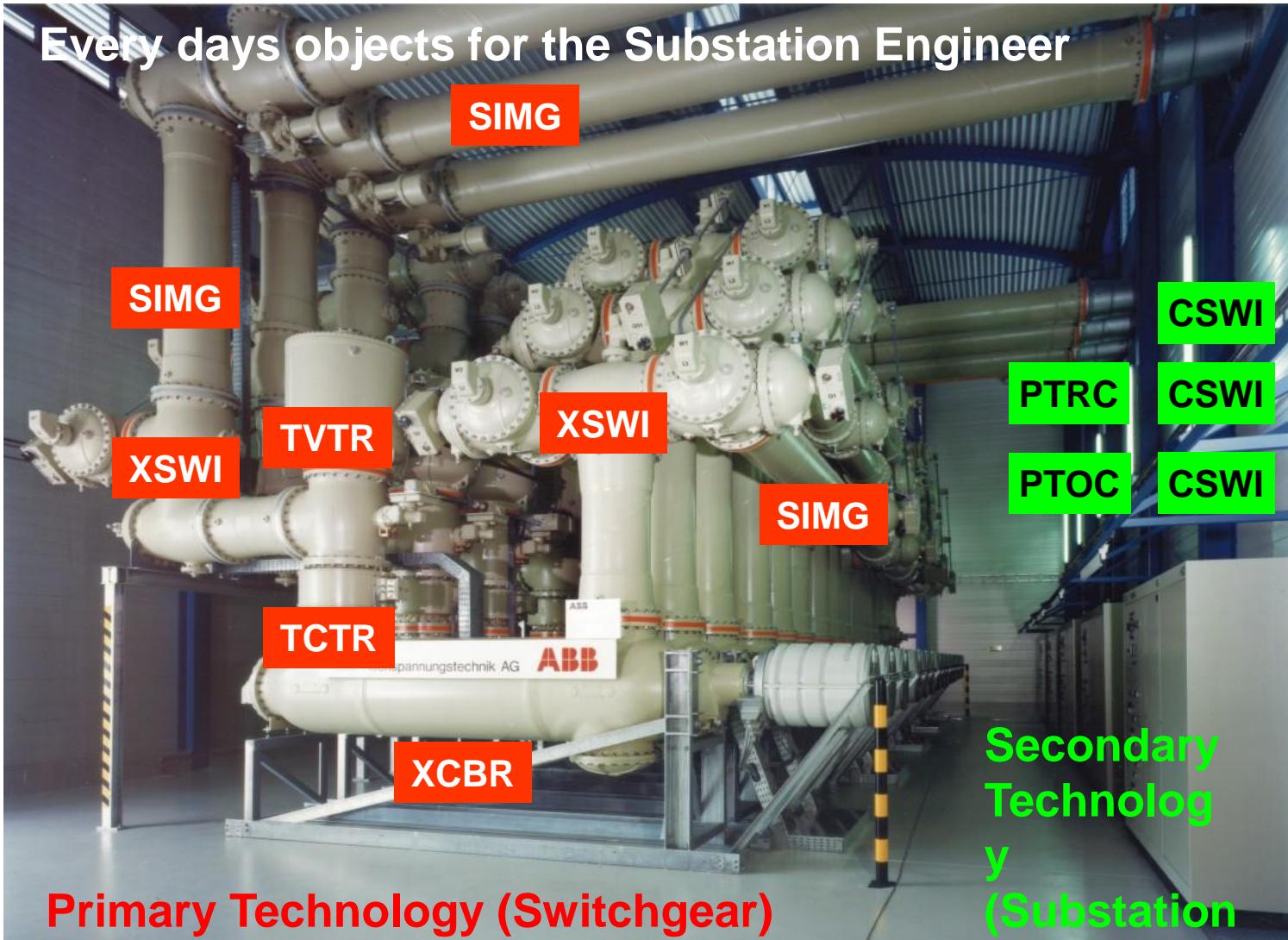
## From conventional to digital

# Digital Substation and IEC61850 Today



# Aspects of IEC 61850 System Integration

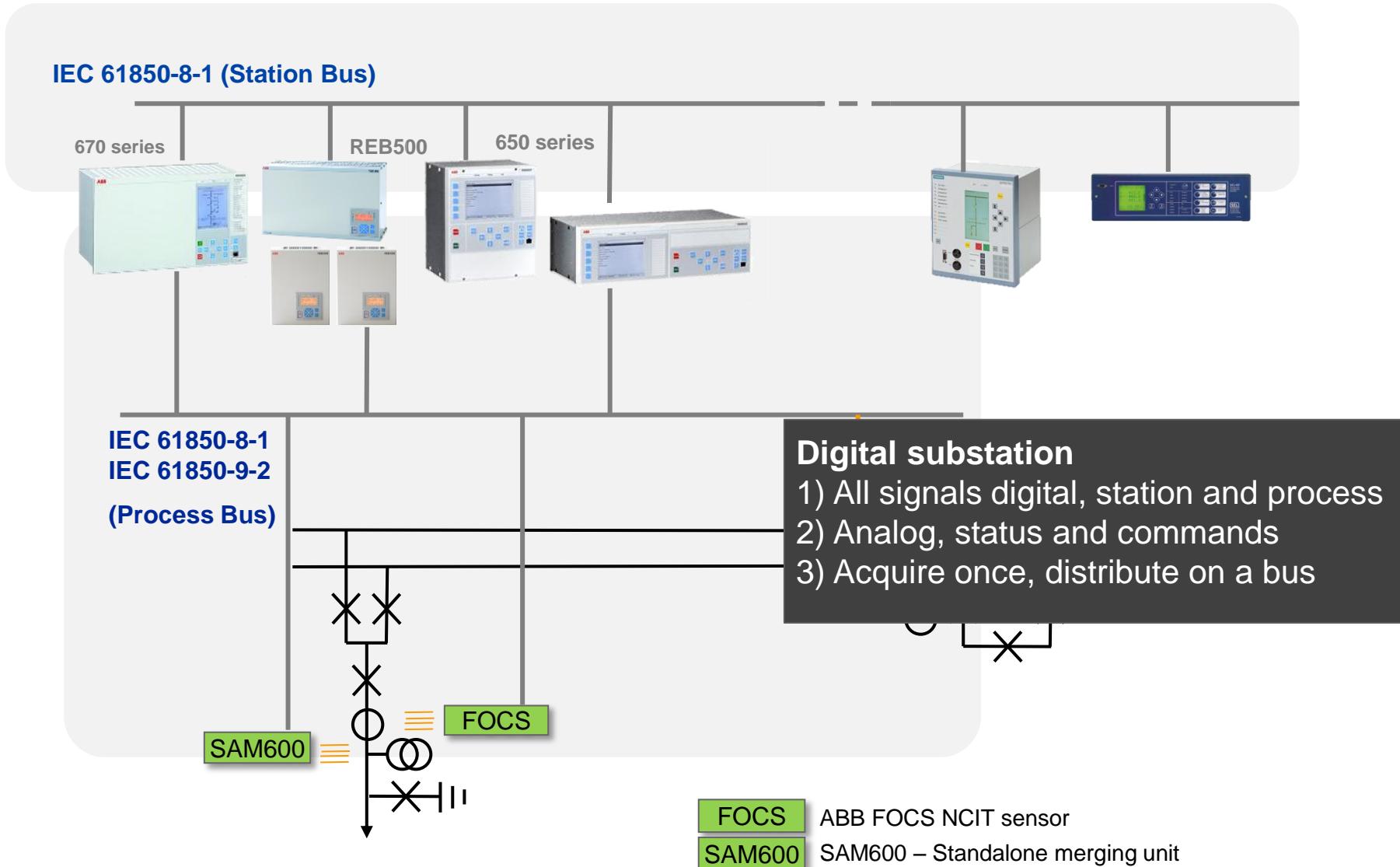
## Standardized Data Model for every Object & Function



Example :  
Object  
Current  
Breaker  
**XCBR**  
What  
data  
belong to  
this object ?

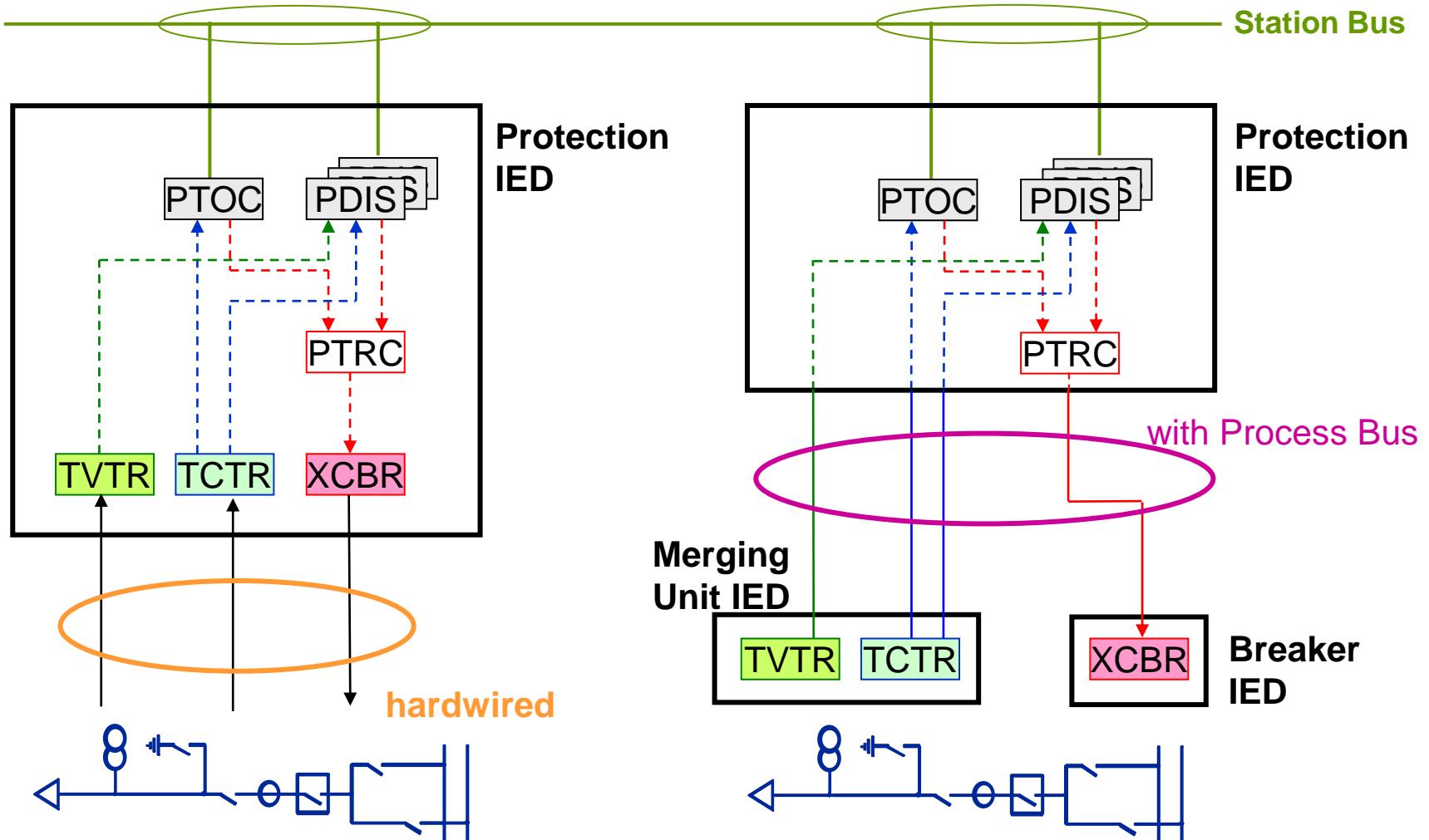
These  
Objects  
are called  
**Logical  
Nodes.**

# Digital Substation and IEC61850 Tomorrow



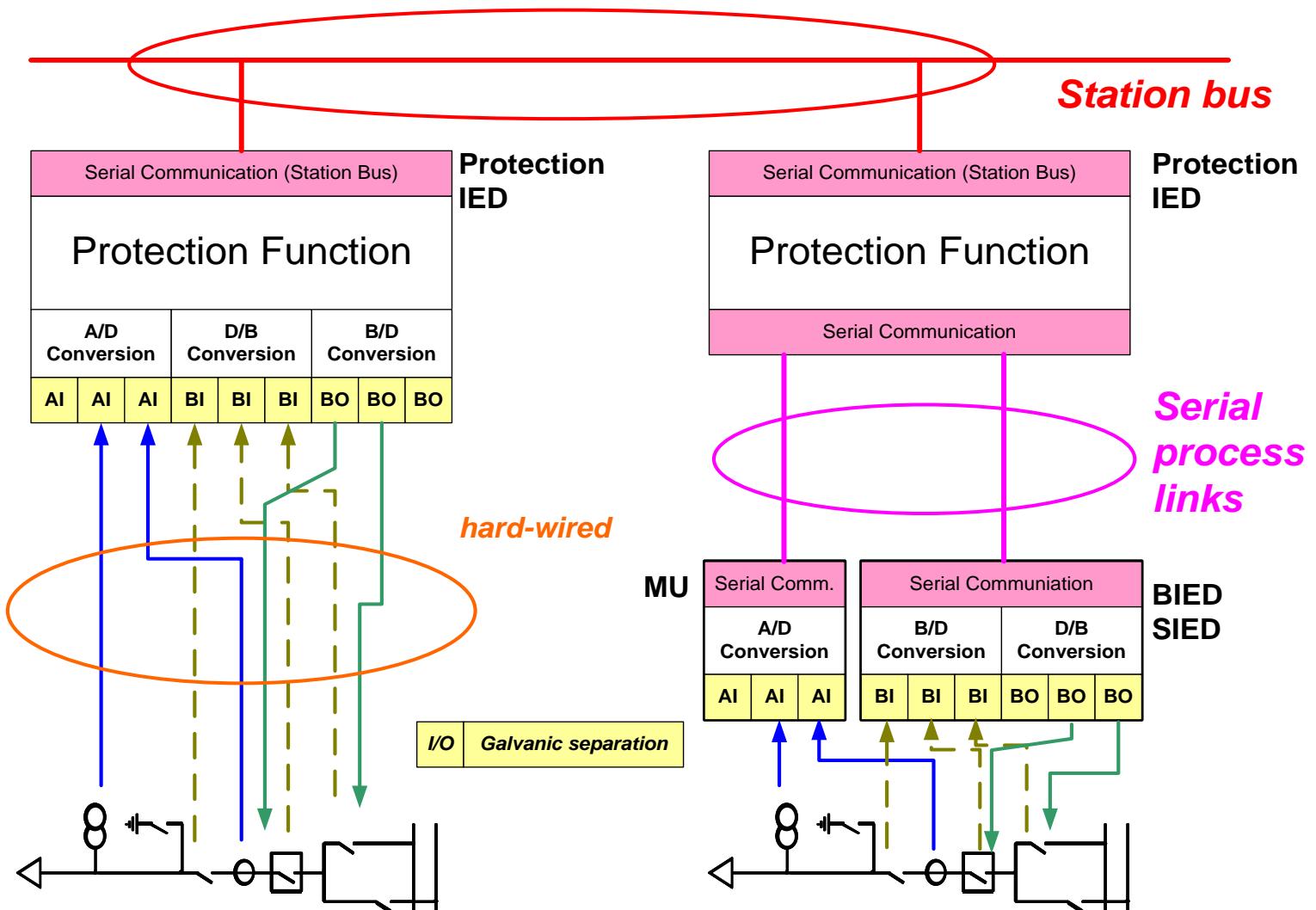
# Introduction to process bus

## Allocation of logical nodes



IEC61850 supports free allocation of functions

# From hardwired process connection to Process Bus Hardware view

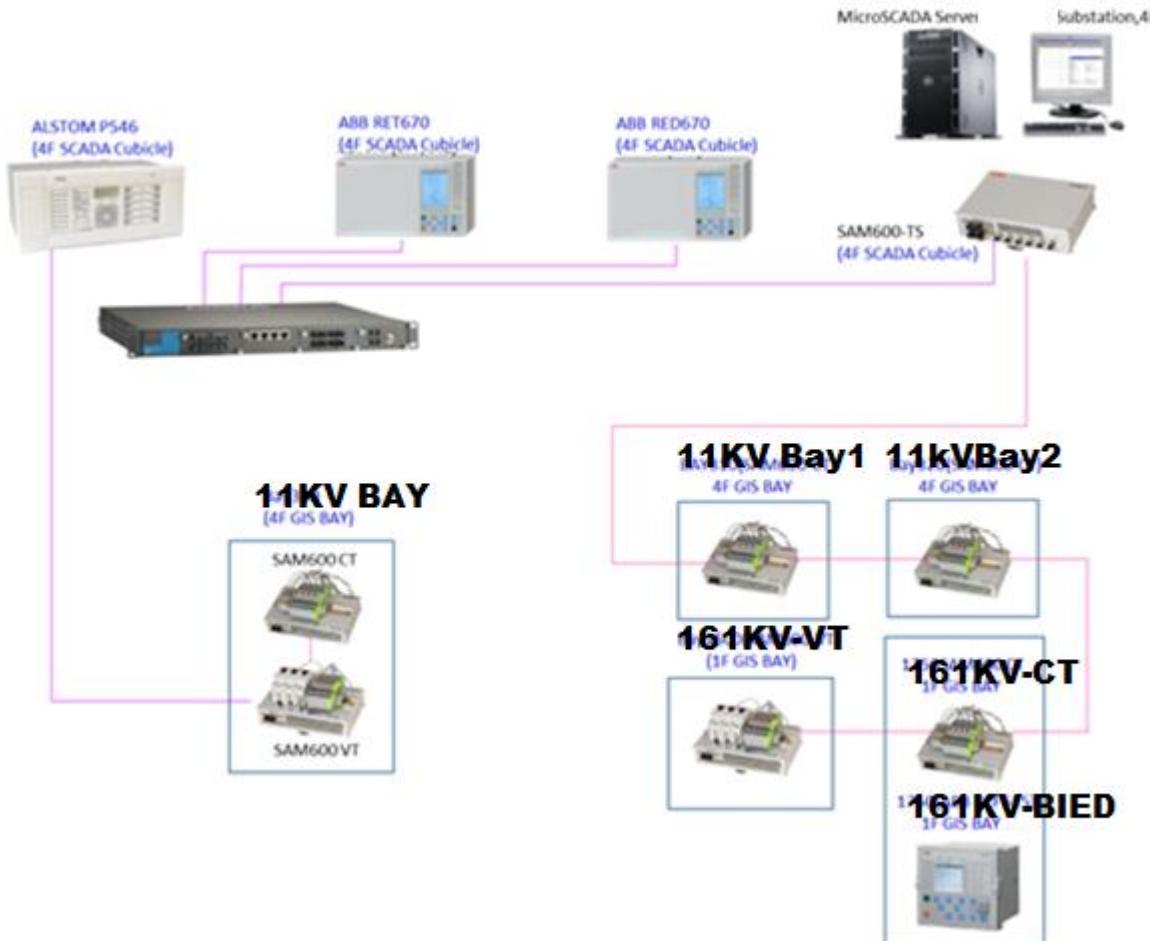


Source : Electra 255 (2011)

# SAM600 1.0

## Taiwan pilot installation

# IEC 61850-9-2 process bus with SAM600 - Taiwan Pilot Installation

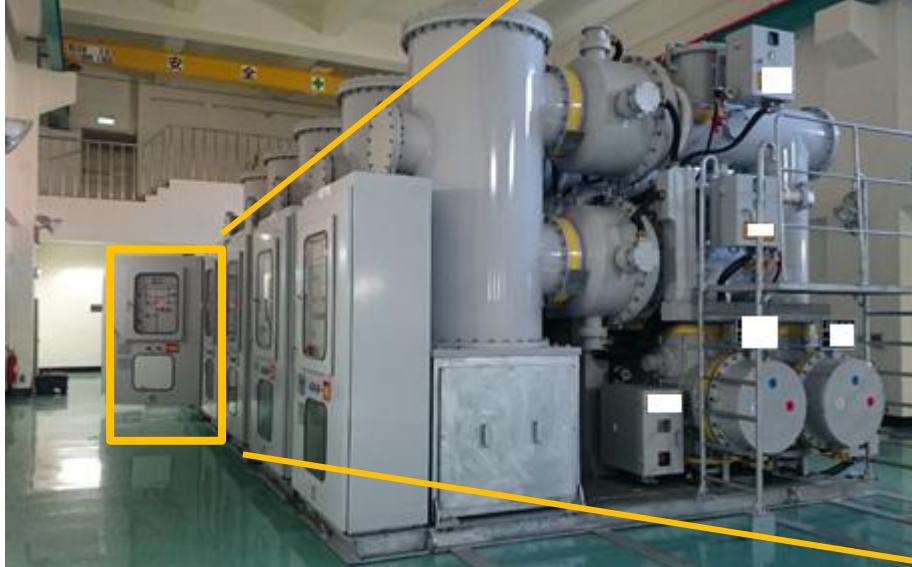


## SAM600 piggy-back installation at a 161kV/11kV transformer feeder

- Station level
  - MicroSCADA Pro HMI
- Bay level with IEC 61850-9-2LE
  - RED670, RET670 Version 2.0
  - Alstom P546
- Process level
  - SAM600 process IO system for integration of conventional CT and VT
  - REF615 for integration of binary signals

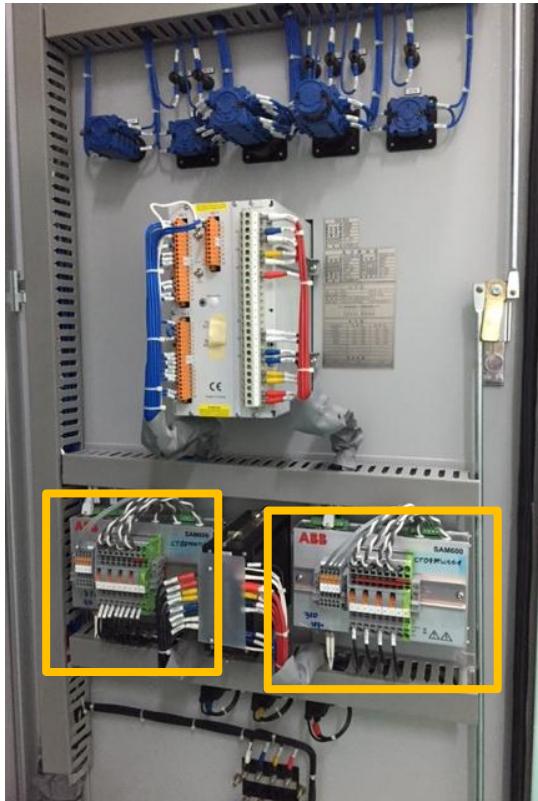
# IEC 61850-9-2 process bus with SAM600 - Taiwan Pilot Installation

- SAM600 modules flexibly placed with minimum impact on existing system
- 161kV GIS local control cubicle:



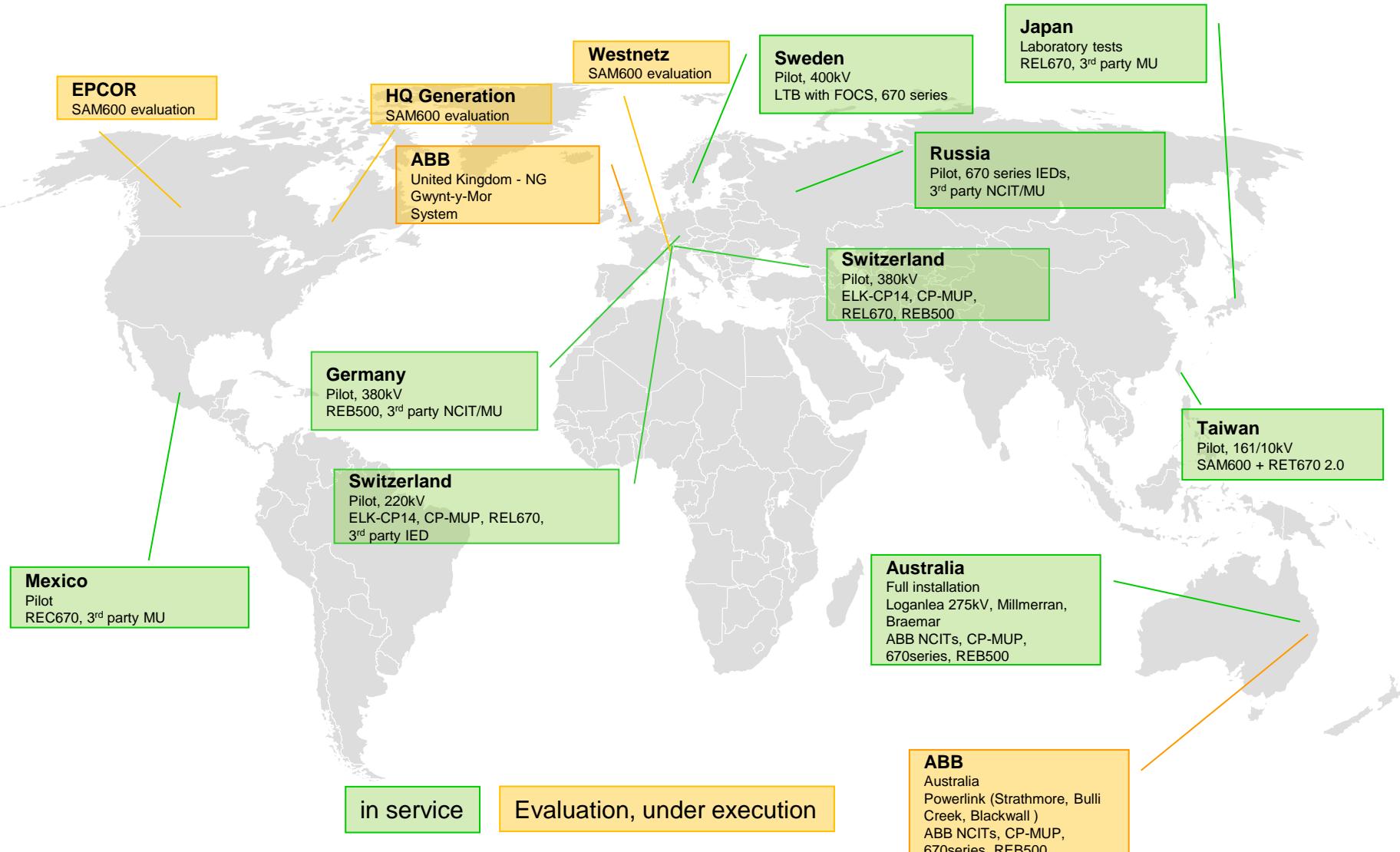
# IEC 61850-9-2 process bus with SAM600 - Taiwan Pilot Installation

- SAM600-CT modules installed on mounting rails installed in...
  - ... 11kV local control and protection panel
  - ... 161kV protection panel



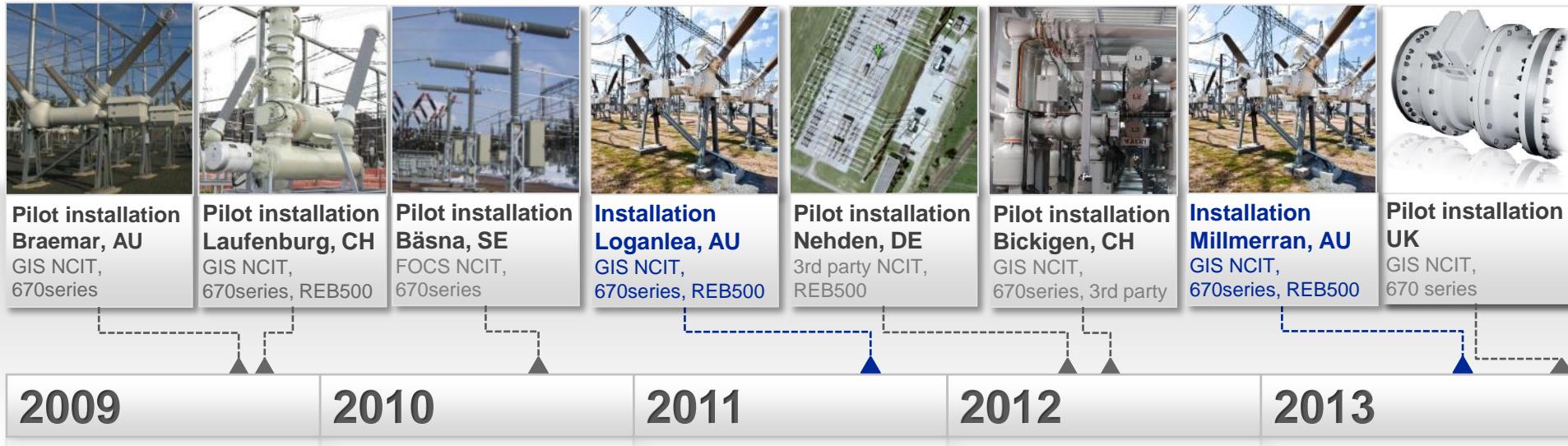
# ABB's experience with IEC 61850-9-2 process bus

## Overview



# ABB's experience with IEC 61850-9-2 process bus

## Completed projects (highlights)



Real experience through real projects

# SAM600 1.0

## Module overview

### Features

# SAM600 – the digital substation enabler



Outdoor cubicle with SAM600 system

- Modular IO system for process bus applications
- Optimized form factor
- Customizable termination of primary signals
- Fully compliant to standards

# SAM600 – the digital substation enabler



SAM600-CT



SAM600-VT



SAM600-TS

**Modular IO system for interfacing primary equipment to IEC 61850 process bus**

- Connects to any conventional current or voltage transformers
- Provides time synchronization
- Optimally adapt to different application types by chanining SAM600 modules into a system

**Compact and optimized form factor**

- DIN-rail mountable for fast installation and replacement
- Installation in station panel or marshalling kiosks

**Termination of primary cabling on SAM600 modules**

- Termination of process and auxiliary signals
- Customizable terminals and standard cabling

# SAM600 – the digital substation enabler



SAM600-CT



SAM600-VT



SAM600-TS

## IEC61850-9-2LE

- 9-2LE with 80 samples/cycle for protection and operational metering
- Quality indication for test switch and fuse failure
- Simulation mode

## Time synchronization

- Synchronizes with 1PPS or runs in free-running mode
- Provides 1PPS outputs for synchronizing bay level devices
- Accuracy 1us or better

## Communication

- Two IEC 61850 access points for IEC 61850-9-2LE traffic
- Each SAM600 module „merges“ local

## Environmental

- Operating temp range: -40°C .. +70°C ambient
- IP class: IP20

# Analog measurements SAM600-CT, SAM600-VT



SAM600-CT



SAM600-VT

## SAM600-CT

- 4 measurement channels @ 1A/5A nom, up to 100x In
  - 1A or 5A order variant
  - Individually calibrated and temperature-compensated
- 1 test switch indication input
  - Indication via 9-2LE quality information

## SAM600-VT

- 3 measurement channels @ 110V nom, up to 2x Un
  - Individually calibrated and temperature-compensated
- 3 fuse failure inputs directly wired via MCBs on the module
  - Indication via 9-2LE quality information

## Communication

- 2 ports for IEC 61850 process bus
- 2 ports for SAM600 system bus
- SAM600 time synchronization via IEEE 1588

# Time synchronization and field gateway SAM600-TS



SAM600-TS

## Time synchronization and gateway functionality

- Synchronize SAM600 to GPS via 1PPS
- Synchronize bay level IEDs via 1PPS
- Synchronize SAM600 system via IEEE1588

## Communication

- 4 ports for IEC 61850 process bus
- 2 ports for SAM600 system bus
- SAM600 time synchronization via IEEE 1588

## IEC 61850-9-2LE gateway

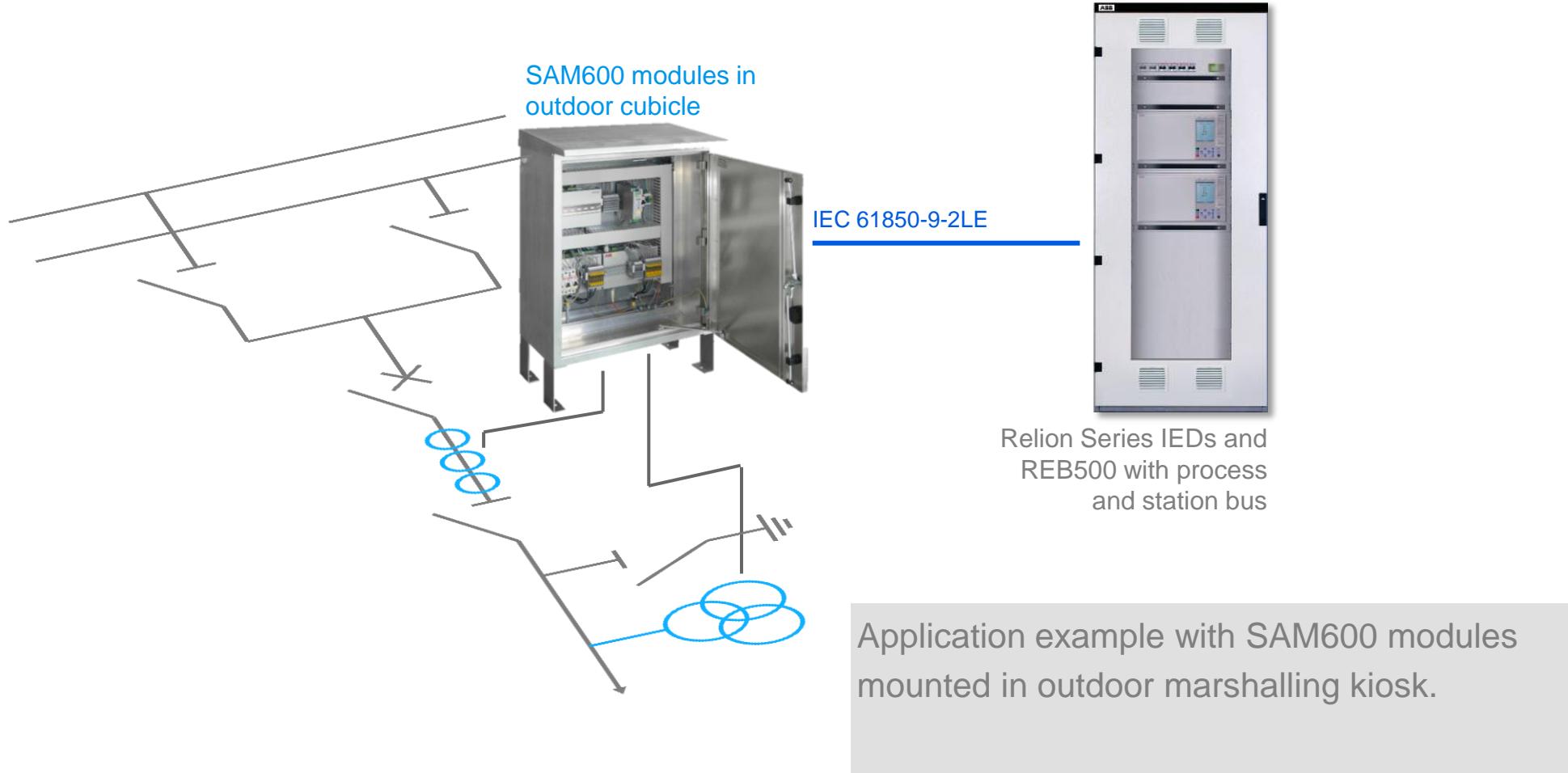
- Receive and forward IEC 61850-9-2LE traffic

# SAM6001.0

## Application examples

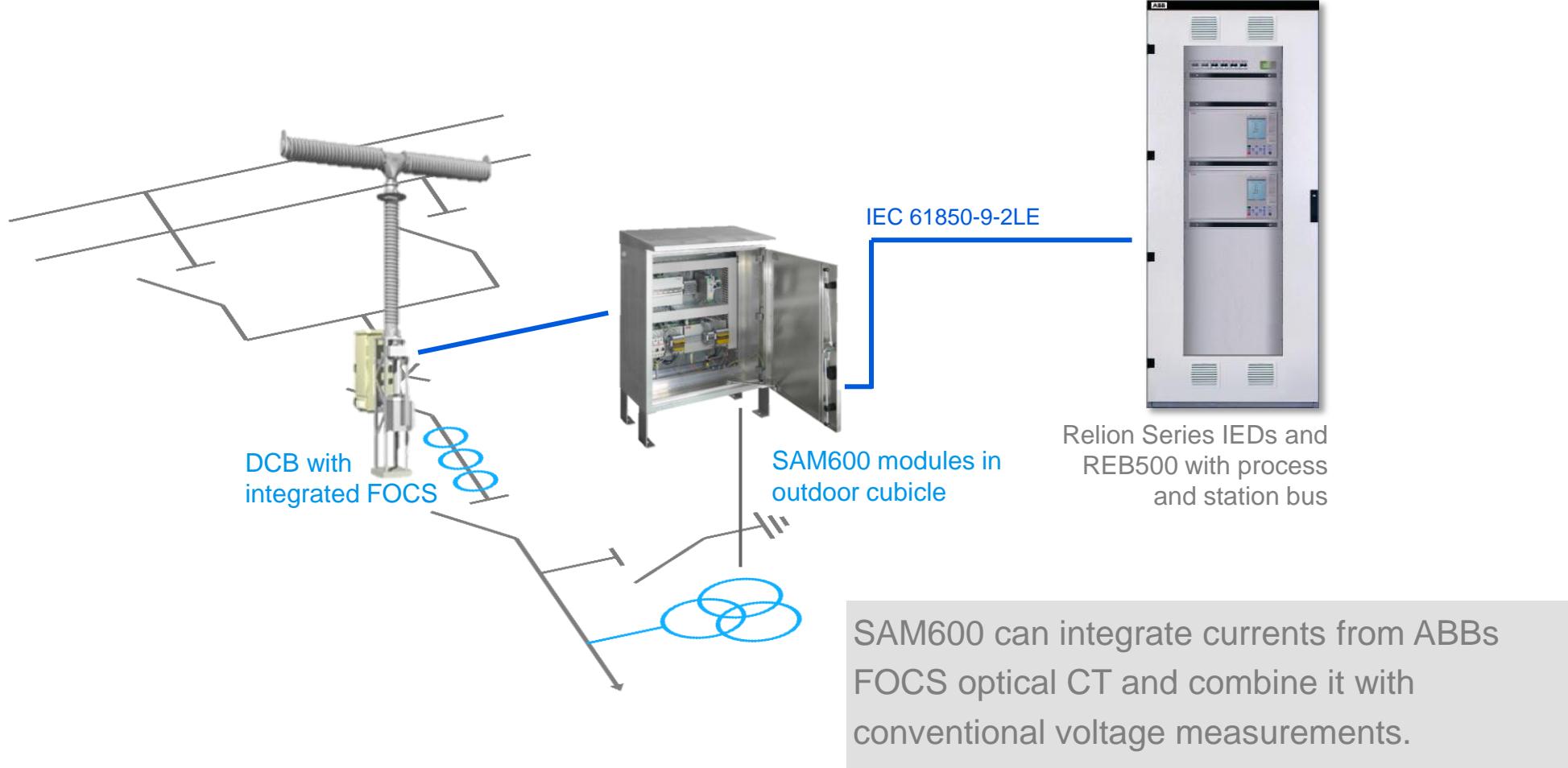
# SAM600 – the digital substation enabler

## Efficient upgrade for conventional substations



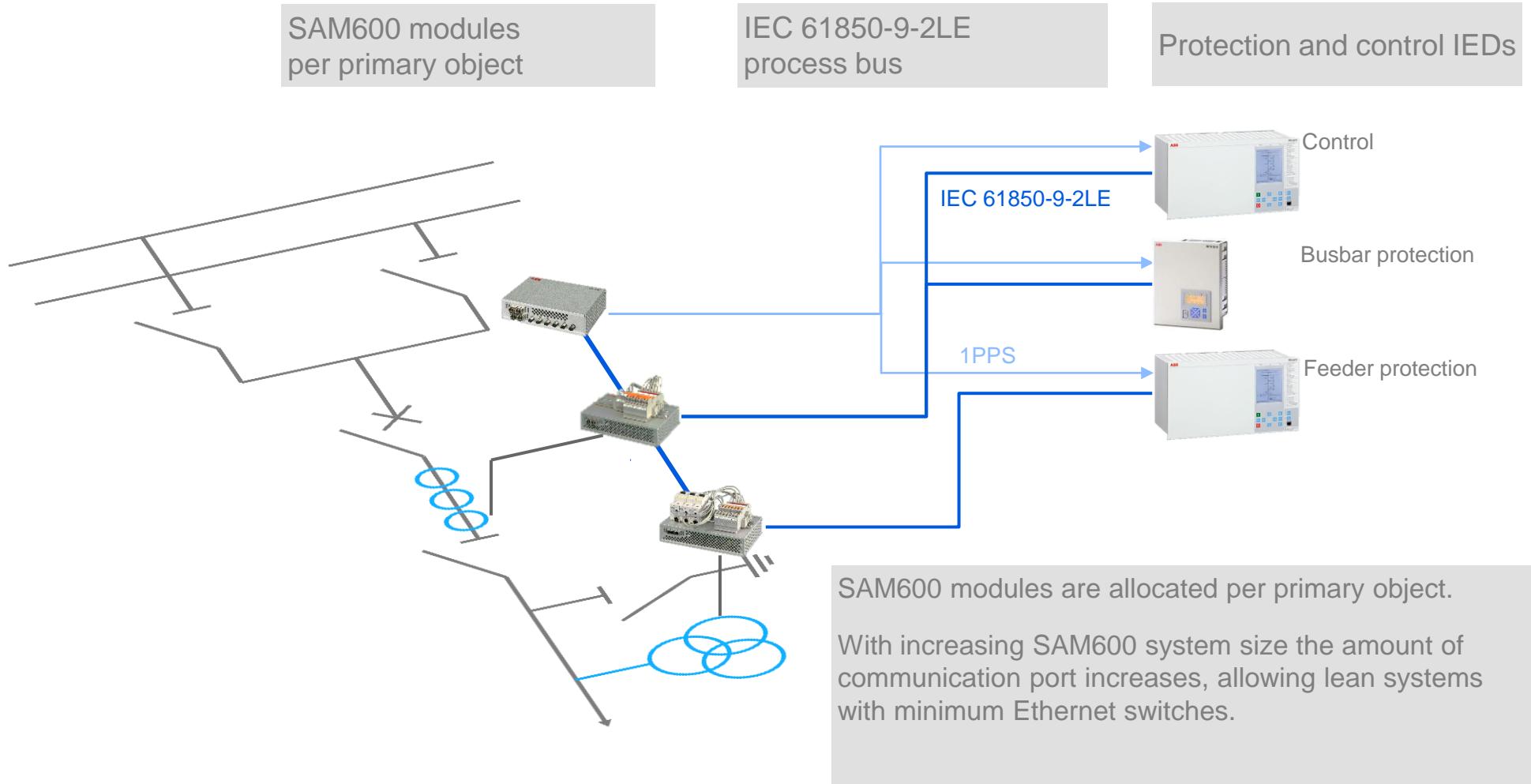
# SAM600 – the digital substation enabler

## Integrates with modern sensors



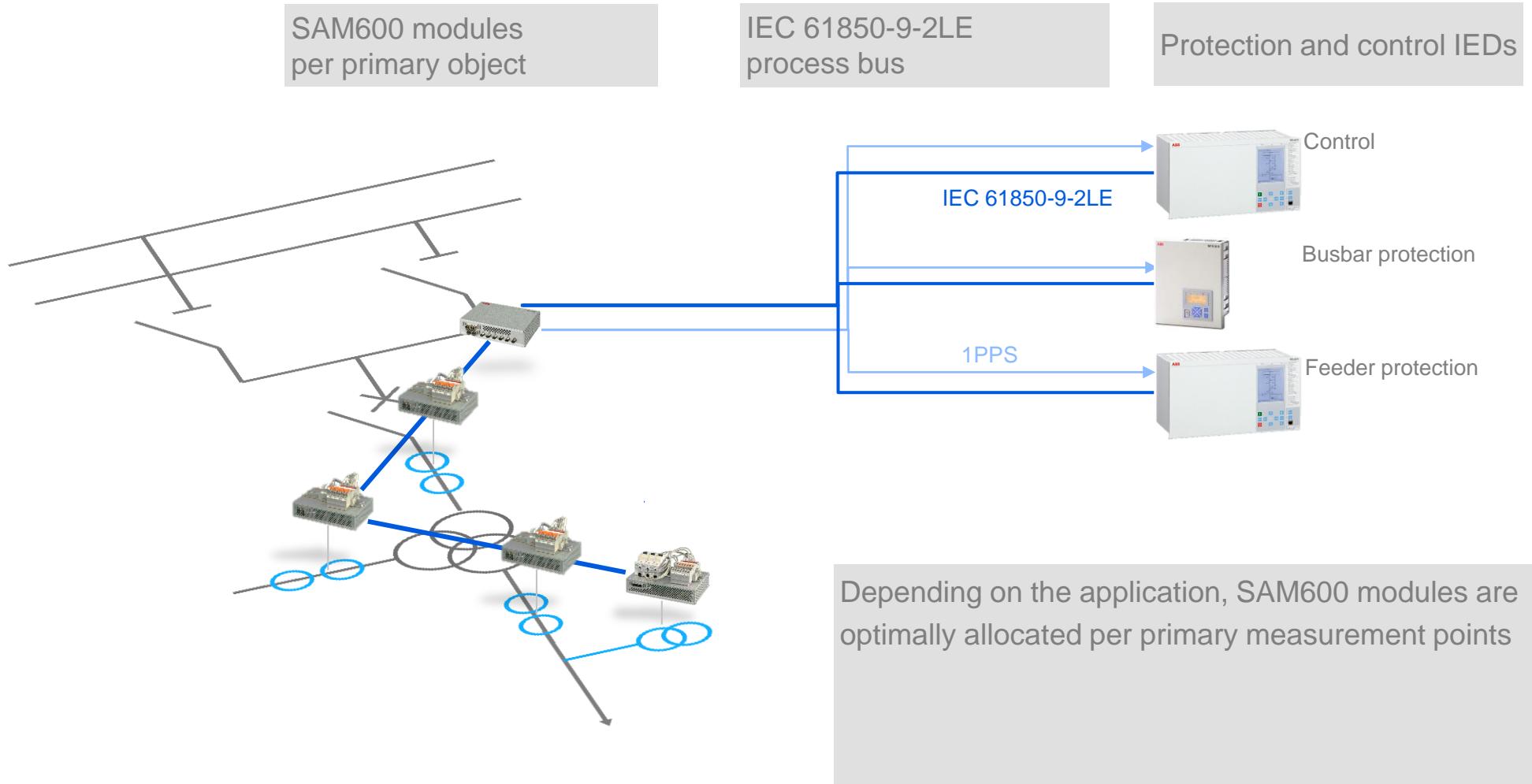
# SAM600 – flexible placement, scalable communication

## Application example – line feeder



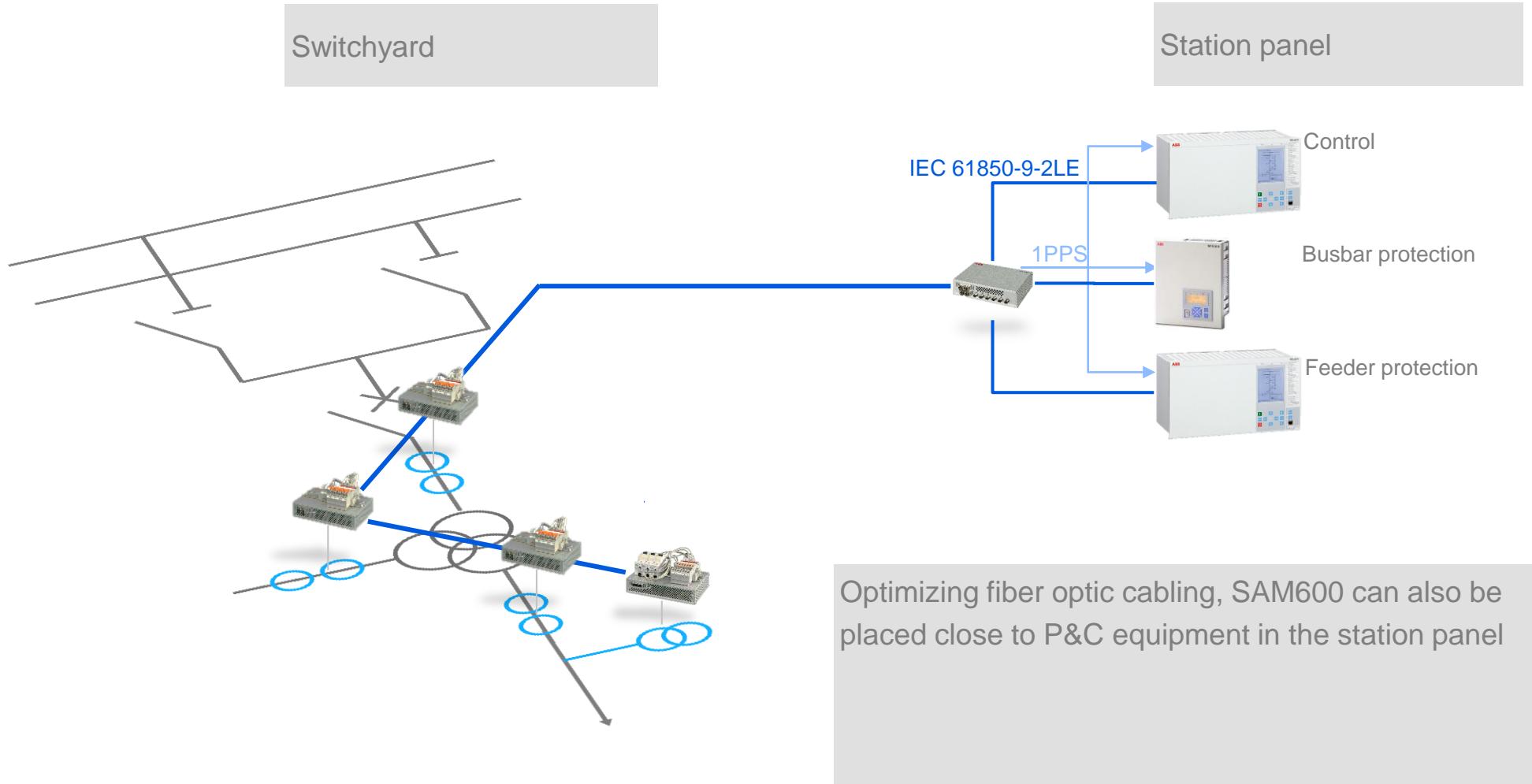
# SAM600 – flexible placement, scalable communication

## Application example – transformer feeder



# SAM600 – flexible placement, scalable communication

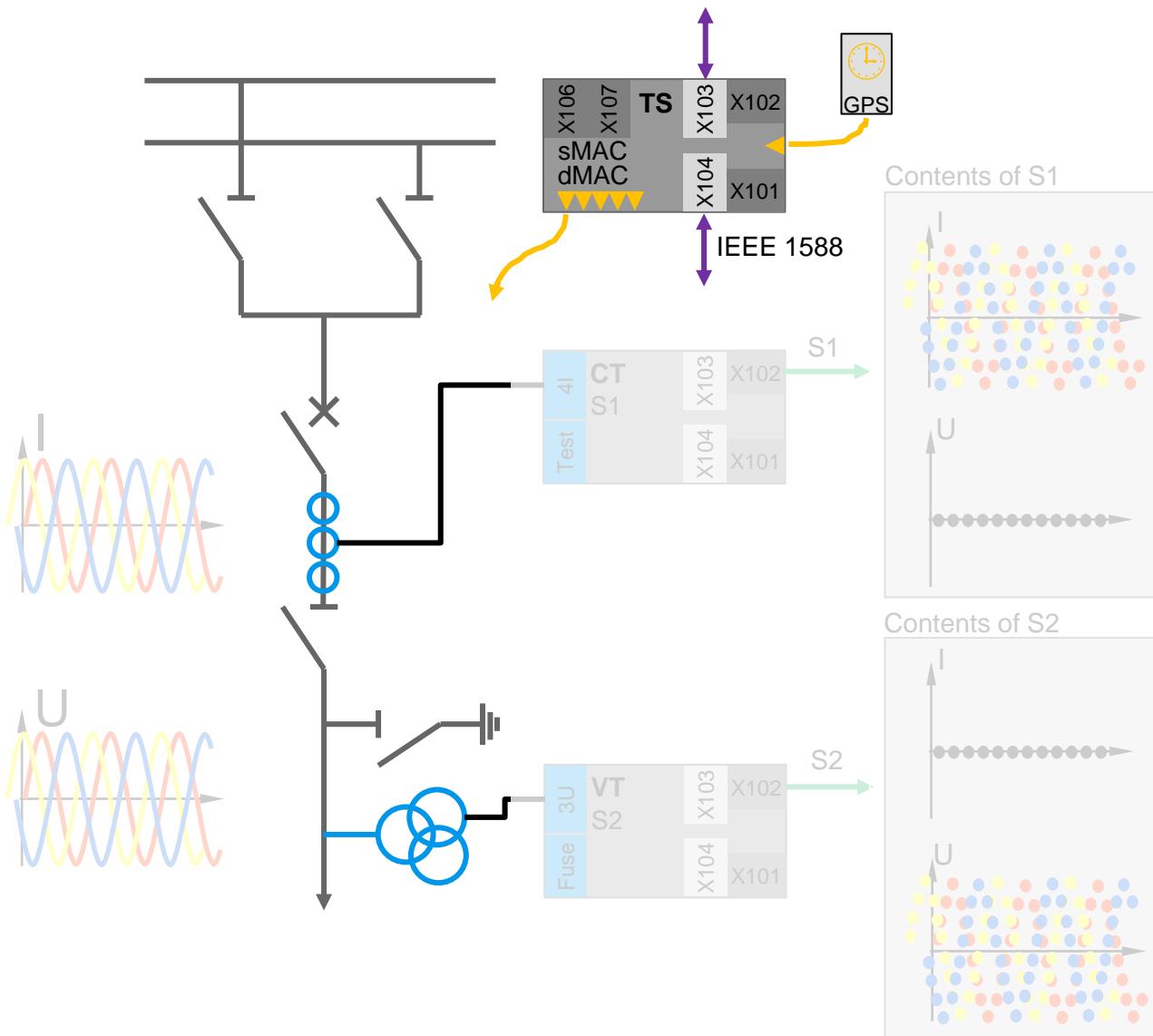
## Application example – split SAM600 setup



# SAM600 1.0

## How it works

# SAM600 provides synchronization mechanisms



- SAM600-TS converts time
  - PPS in → IEEE 1588
  - IEEE 1588 → PPS out
- Synchronize SAM600 against a GPS grandmaster
- Synchronize IEDs or other merging units with via PPS

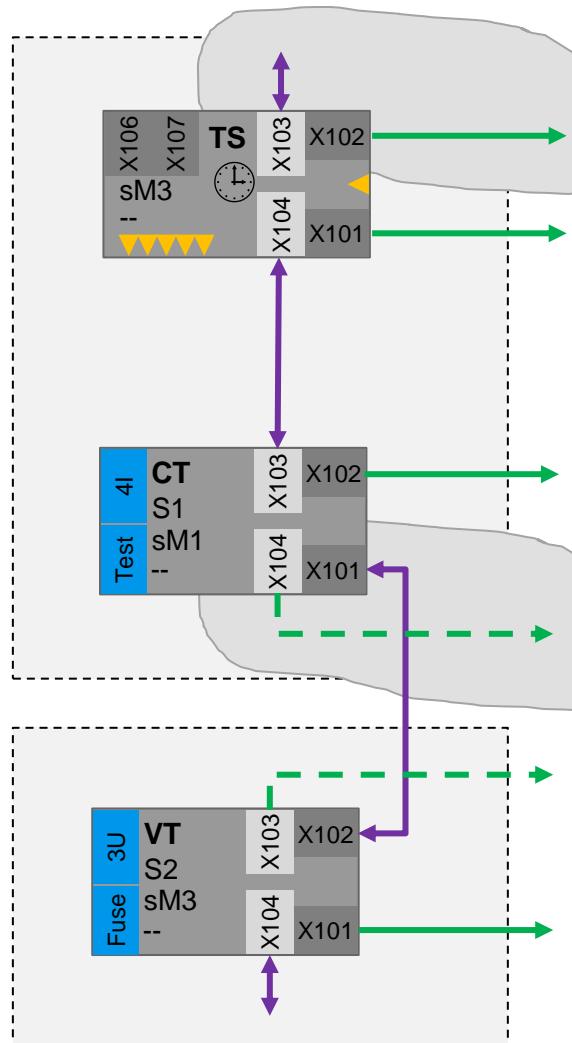
# Communication ports of SAM600



Optical port  
Electrical port

- Each SAM600 module has 4 communication ports
- SAM600 system bus
  - 2 ports, default: X103/X104
  - Tx/Rx, 9-2LE, IEEE 1588
- SAM600 uplink ports to IED
  - 2 ports, default: X101/X102
  - Tx only, 9-2LE
- System bus and uplink ports work in pairs. Their behavior can be swapped
- SAM600 bridge-in ports
  - X106/X107 on SAM600-TS
  - Rx only, 9-2LE

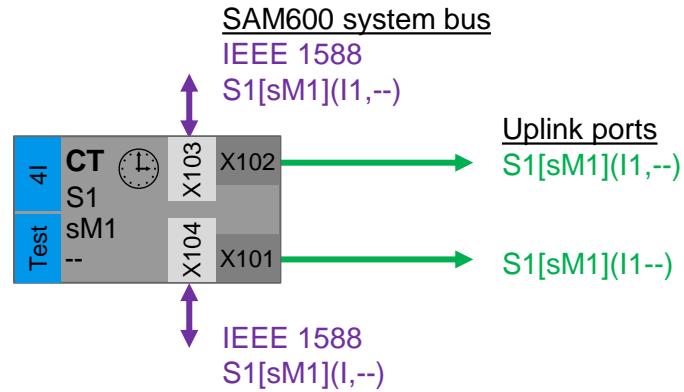
# SAM600 modules in different compartments



- Each RJ45/SFP is a port pair
  - Those pairs can be switched in their behavior
- Default settings
  - System bus = RJ45
  - Uplink ports = SFP
- SAM600 modules in same physical compartment
  - Use the system bus over RJ45 in order to chain SAM600 modules
- SAM600 modules located in physically different compartments
  - Use port switch on two modules in order to run system bus over SFP

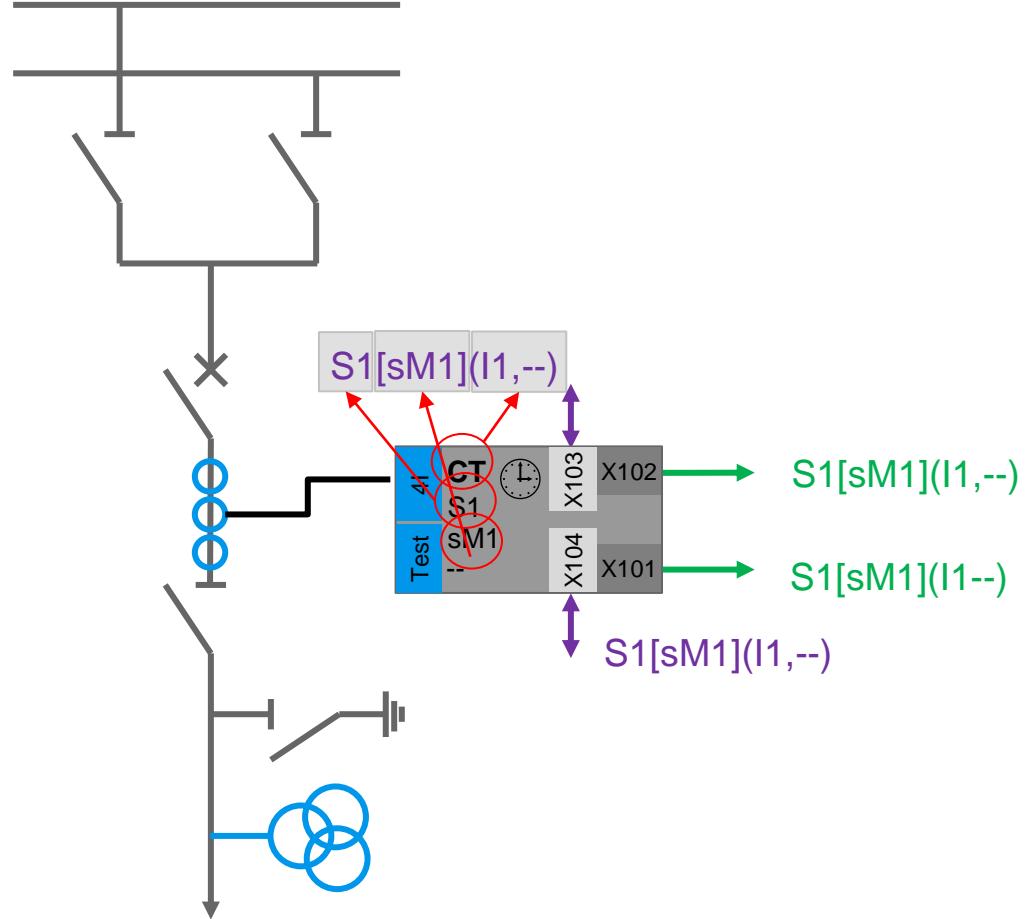
# SAM600 system bus and SAM600 uplink ports

## Definition



- SAM600 system bus
  - Synchronize several SAM600 modules via IEEE 1588
  - Each SAM600 puts its local stream on the system bus
  - Tx and Rx
- Uplink ports
  - Only 9-2LE streams are sent on these ports, Tx only
  - Each uplink can connect to an IED or a switch

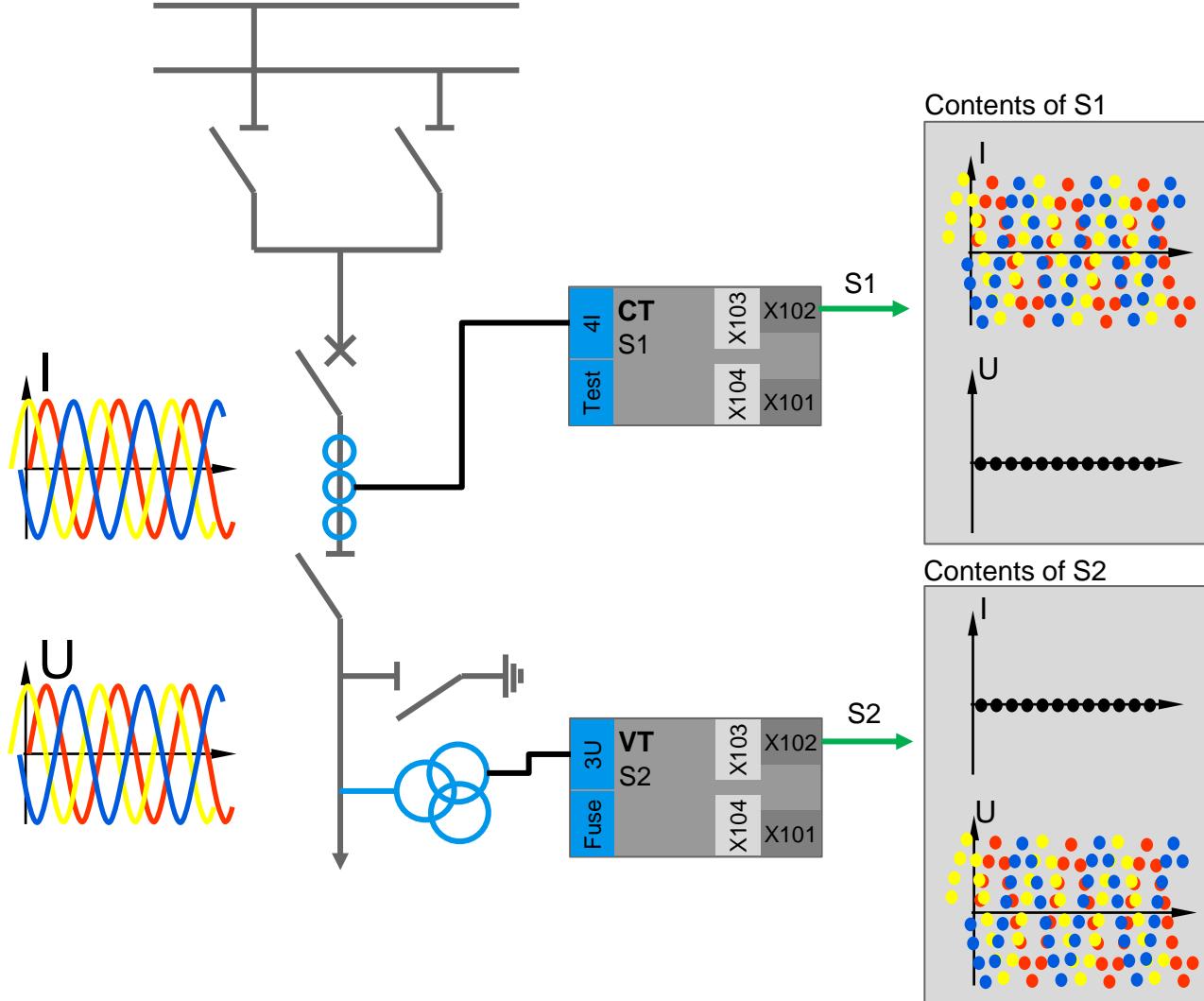
# Understanding the nomenclature



S1 -- svID  
[sM1] -- sourceMAC  
(I1,--) -- content of 9-2LE dataset  
Currents I1, no voltages

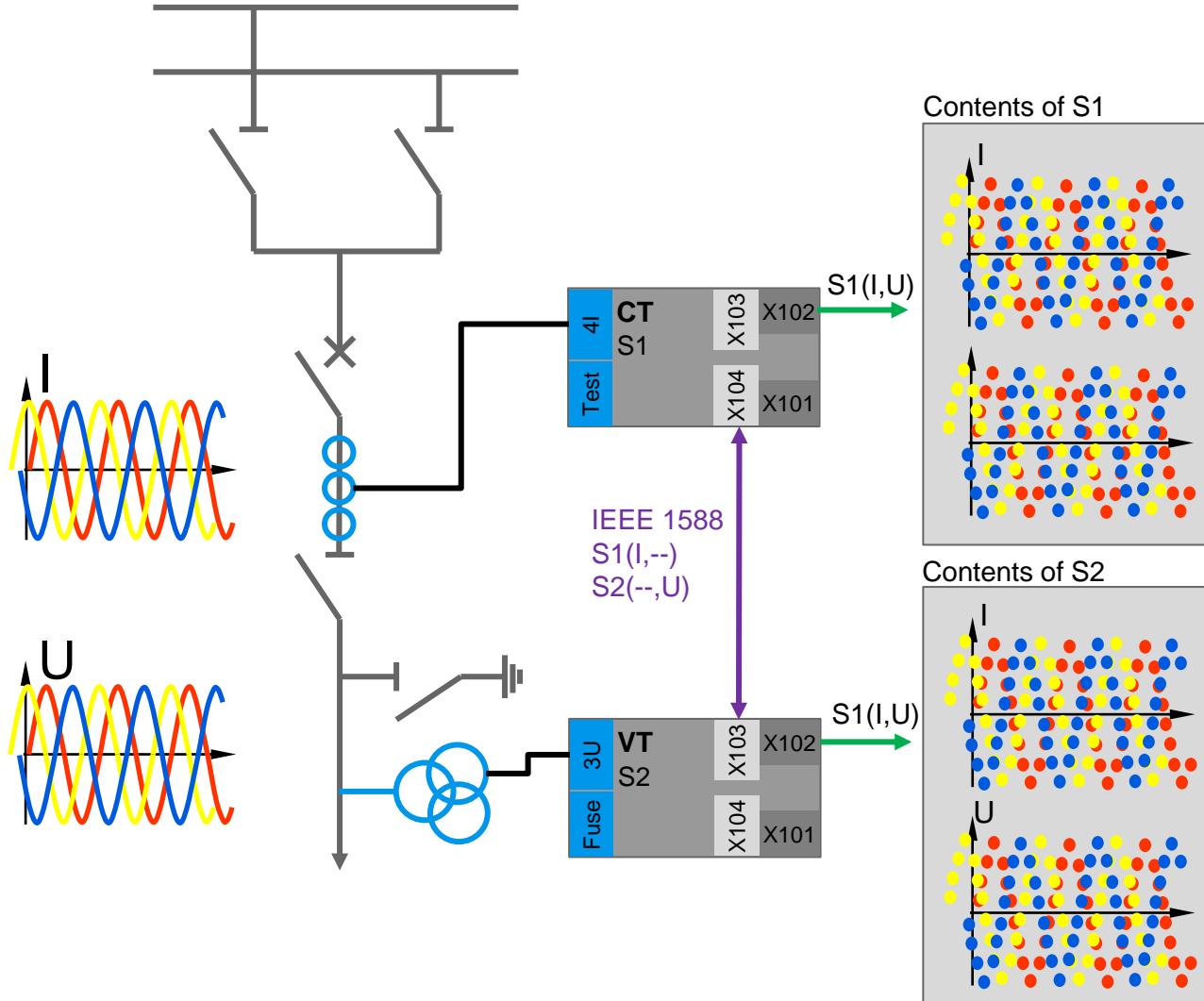
↔ SAM600 system bus. Tx/Rx  
→ SAM600 uplink port. Tx

# SAM600 converts analog input to IEC 61850-9-2LE



- Each SAM600 module is a self-contained standalone merging unit
- Analog → digital conversion
  - SAM600-CT: currents
  - SAM600-VT: voltages

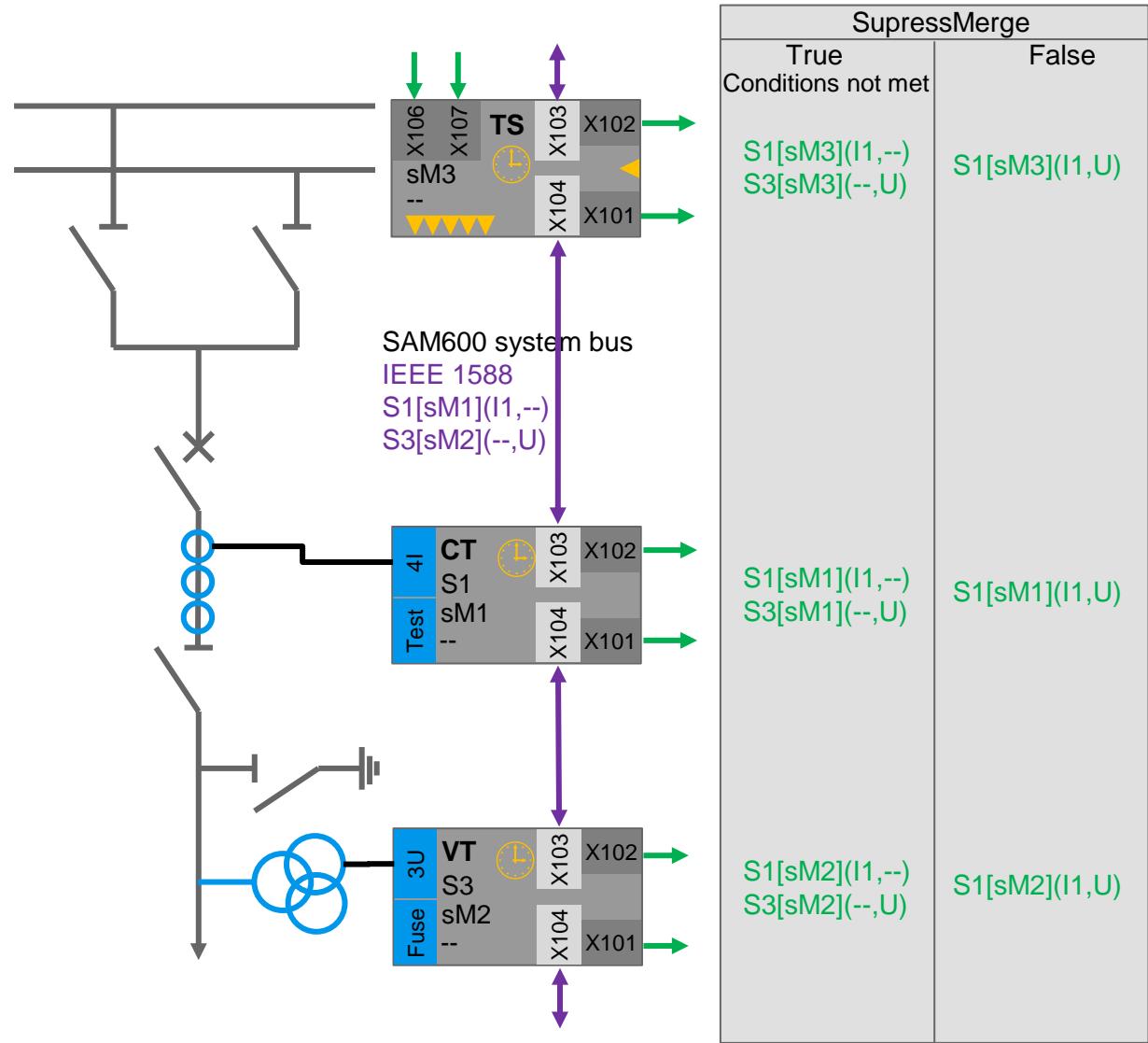
# SAM600 merges IEC 61850-9-2LE streams



- If chained to a SAM600 system, SAM600 modules merge „opposite“ 9-2LE streams on the uplink ports
  - Certain conditions apply
- Usage
  - Directly connect IED devices on uplink ports, not using switches
  - Reduce # of streams send to the IED

# SAM600 merges IEC 61850-9-2LE streams

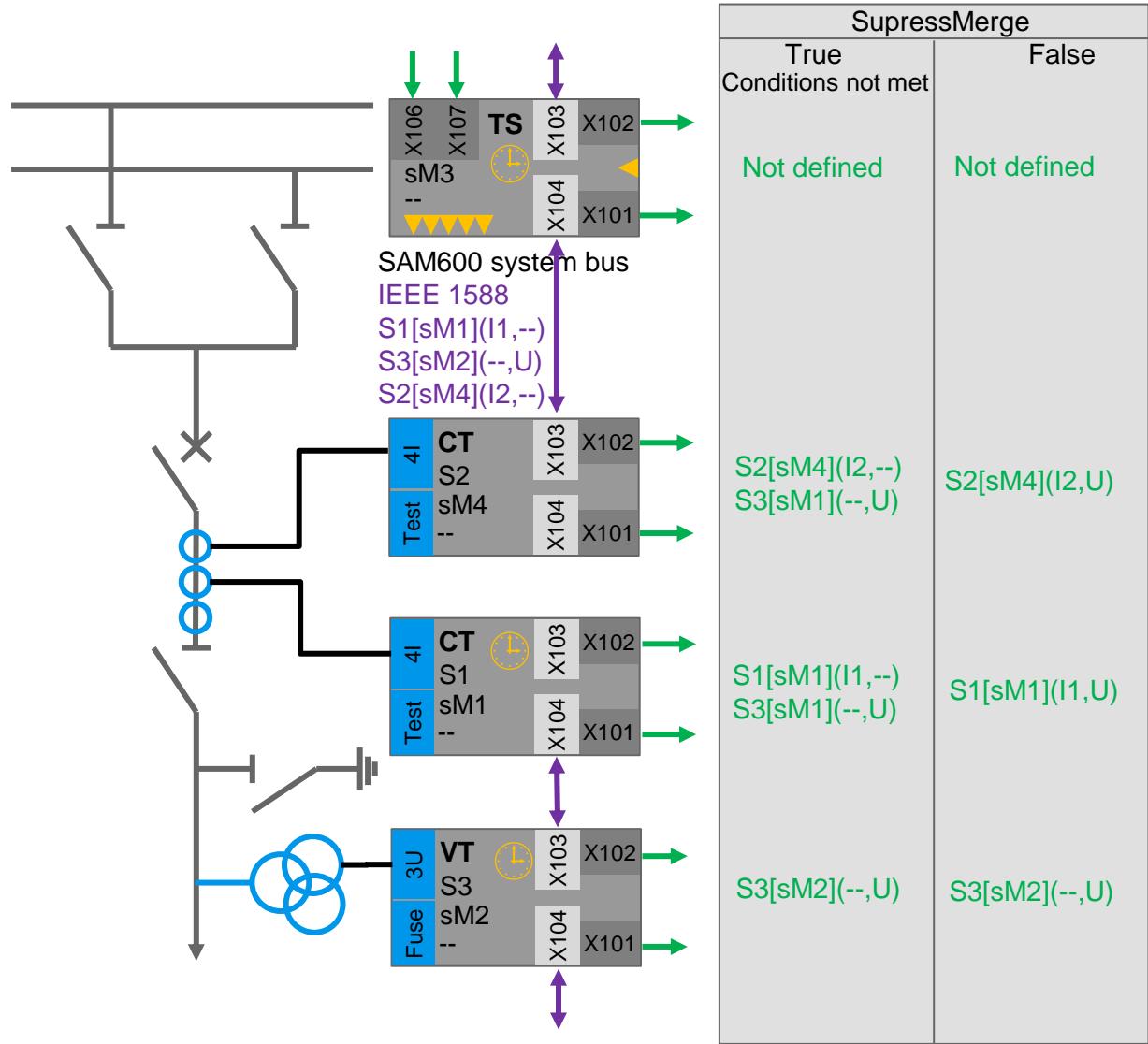
## Standard behavior



- Each SAM600 module „merges“ opposite measurements and provides them on its uplink ports
- Rules
  - Samples must be in sync
  - Only „opposite“ measurements can be merged into a 9-2LE stream
  - sVID from CT is used
  - sMAC from the module from where the stream „leaves“ is used
  - Merging can be suppressed per module
  - IEEE 1588 is not available on uplink ports
- Merging is suspended or resumed based on rules
- smpSync is set according to „RequirePPS“ parameter

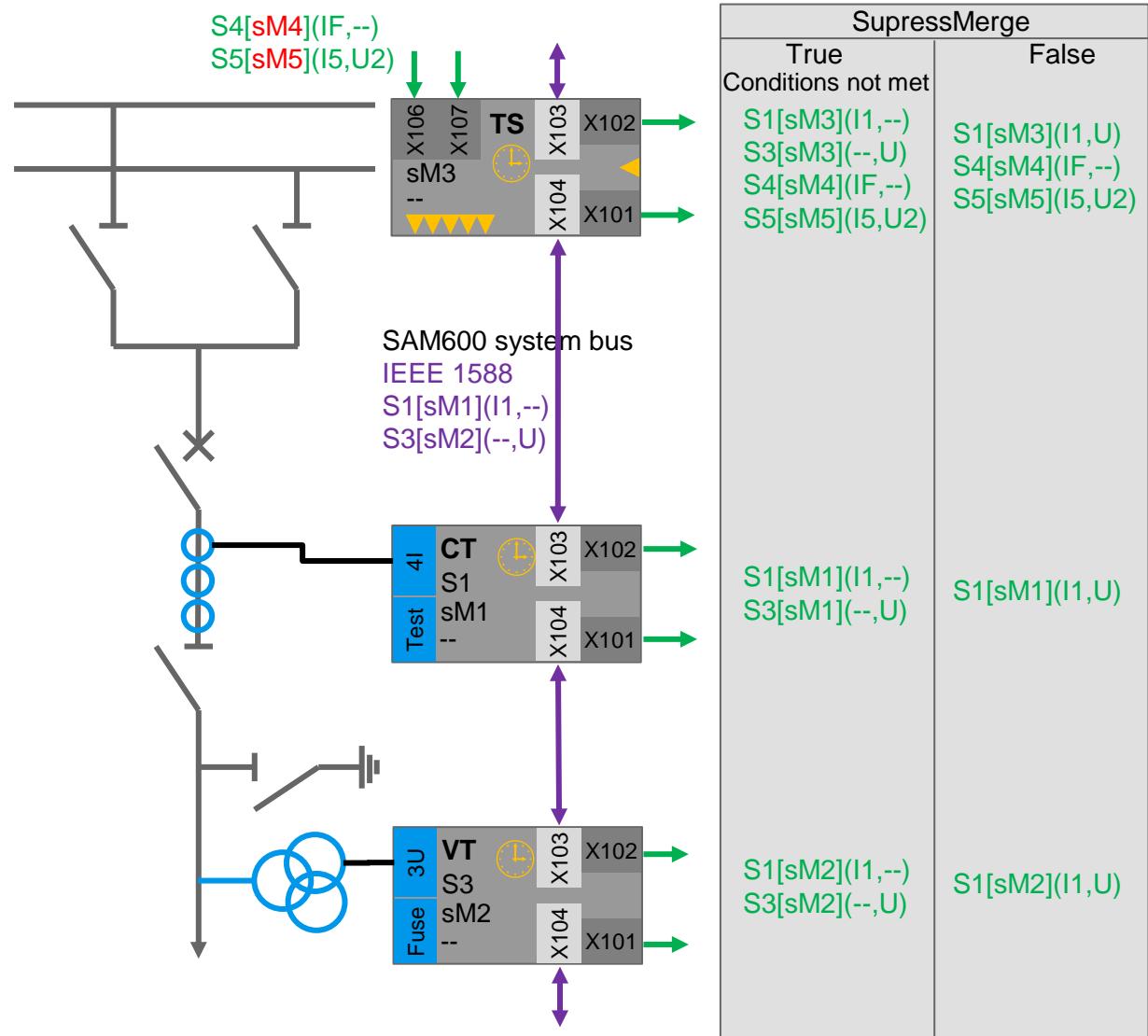
# SAM600 merges IEC 61850-9-2LE traffic

## More than one SAM600-CT module



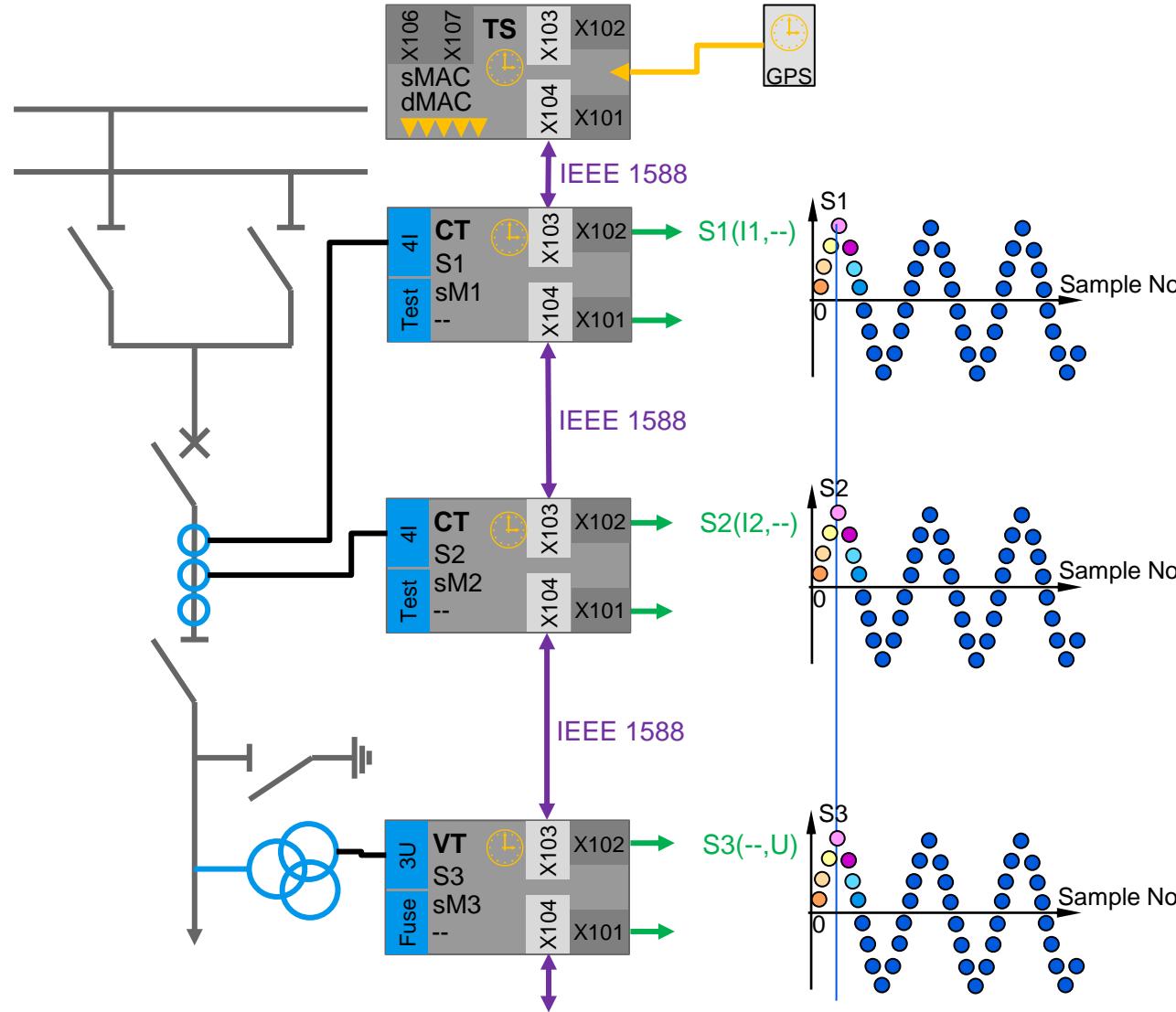
- Possible to chain multiple SAM600-CT modules
  - N SAM600-CT
  - 1 SAM600-VT
  - 1 SAM600-TS
- Each SAM600-CT provides its measurements together with voltage measurements
- SAM600-VT sends just its own measurements on the uplink
- Output on SAM600-TS is undefined
- Alternatives
  - Connect system bus to IED
  - smpSync is always true, irrespective of RequirePPS setting

# SAM600 merges IEC 61850-9-2LE streams Bridging in external 9-2LE traffic from sensors



- SAM600-TS has two additional bridging ports
  - X106, X107
  - 9-2LE traffic received on those ports is forwarded to the ports X101 and X102 of SAM600-TS
  - Traffic received on those ports is not shared on the SAM600 system bus
  - Traffic contents are not modified
  - Traffic contents are not merged
- Usage
  - Integration of a FOCS sensor
  - FOCS sensor must be synced with PPS to SAM600

# Using SAM600-TS for synchronizing SAM600 system



- Synchronization is achieved via the SAM600-TS module
  - Translates between PPS and IEEE 1588
  - Chained SAM600 modules synchronize via the system bus through IEEE 1588
- All sampling across all modules is synchronized
  - Jitter <50ns
  - smpCnt = 0 on the receiver appears for all streams within the jitter window
  - → Protection ok
- Setting „RequirePPS“
  - If GPS connected → smpSync = true
  - If no GPS → smpSync = false

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